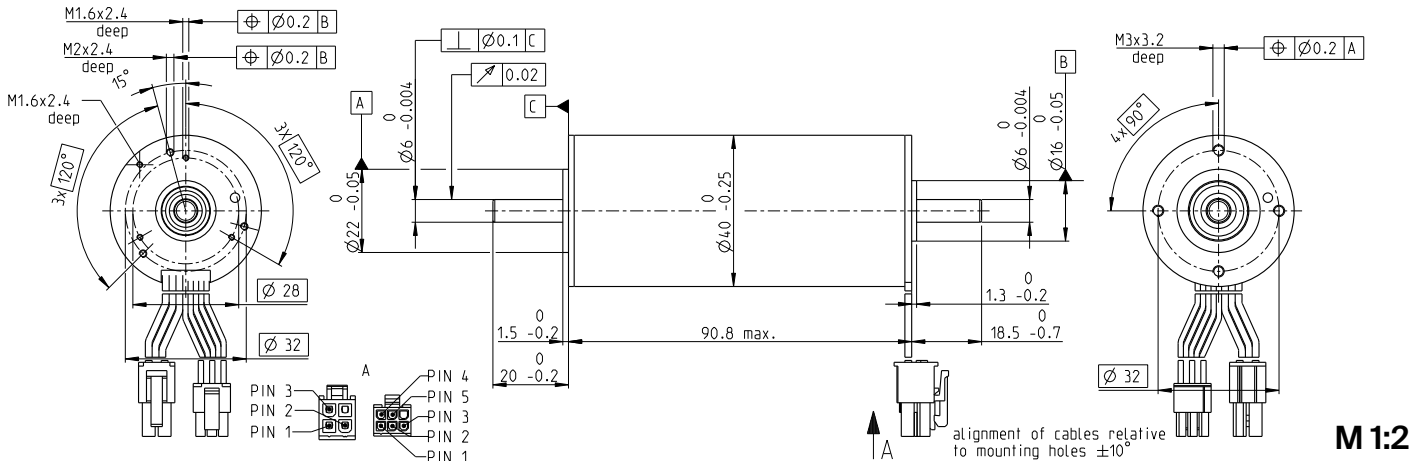


EC-i 40 Ø40 mm, brushless, 130 Watt

High Torque

NEW

EC-i



- Stock program
- Standard program
- Special program (on request)

Part Numbers

with Hall sensors

666601	676600	666602	666603
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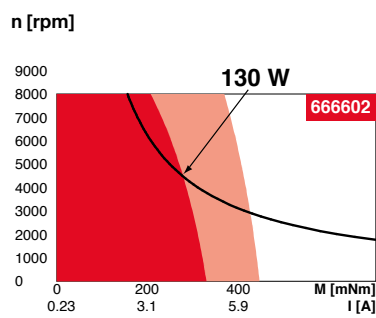
Motor Data

Values at nominal voltage		18	24	36	48
1 Nominal voltage	V	18	24	36	48
2 No load speed	rpm	4670	4730	4670	4640
3 No load current	mA	496	379	248	185
4 Nominal speed	rpm	3920	3990	3940	3910
5 Nominal torque (max. continuous torque)	mNm	276	299	327	340
6 Nominal current (max. continuous current)	A	7.38	6.01	4.27	3.29
7 Stall torque ¹	mNm	3320	4090	4950	5360
8 Stall current	A	91	85	68	55
9 Max. efficiency	%	85.9	87.2	88.4	88.8
Characteristics					
10 Terminal resistance phase to phase	Ω	0.198	0.281	0.529	0.876
11 Terminal inductance phase to phase	mH	0.128	0.222	0.512	0.922
12 Torque constant	mNm/A	36.4	47.9	72.8	97.8
13 Speed constant	rpm/V	262	199	131	97.7
14 Speed/torque gradient	rpm/mNm	1.420	1.170	0.953	0.875
15 Mechanical time constant	ms	1.16	0.956	0.778	0.715
16 Rotor inertia	gcm ²	78	78	78	78

Specifications

Thermal data	
17 Thermal resistance housing-ambient	5.08 K/W
18 Thermal resistance winding-housing	0.6 K/W
19 Thermal time constant winding	18.5 s
20 Thermal time constant motor	1490 s
21 Ambient temperature	-40...+100°C
22 Max. winding temperature	+155°C
Mechanical data (preloaded ball bearings)	
23 Max. speed	8000 rpm
24 Axial play at axial load < 9.0 N	0 mm
> 9.0 N	0.15 mm
25 Radial play	preloaded
26 Max. axial load (dynamic)	7 N
27 Max. force for press fits (static) (static, shaft supported)	87 N
28 Max. radial load, 5 mm from flange	3000 N
	29.9 N

Operating Range



Comments

- Continuous operation**
In observation of above listed thermal resistance (lines 17 and 18) the maximum permissible winding temperature will be reached during continuous operation at 25°C ambient.
= Thermal limit.
- Short term operation**
The motor may be briefly overloaded (recurring).
- Assigned power rating**

Other specifications

- 29 Number of pole pairs
- 30 Number of phases
- 31 Weight of motor

Values listed in the table are nominal.

Connection motor (Cable AWG 20)		
red	Motor winding 1	Pin 1
black	Motor winding 2	Pin 2
white	Motor winding 3	Pin 3
	N.C.	Pin 4

Connector Article number		
Molex	39-01-2040	

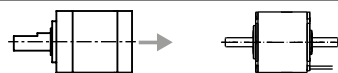
Connection sensor (Cable AWG 26)		
yellow	Hall sensor 1	Pin 1
brown	Hall sensor 2	Pin 2
grey	Hall sensor 3	Pin 3
blue	GND	Pin 4
green	V _{Hall} 4.5...24 VDC	Pin 5
	N.C.	Pin 6

Connector Article number	
Molex	430-25-0600

Wiring diagram for Hall sensors see p. 49
¹Calculation does not include saturation effect (p. 61/168)

maxon Modular System

- 8
- 3
- 587 g
- Planetary Gearhead**
- Ø42 mm
- 3 - 15 Nm
- Page 398



Details on catalog page 36

- Recommended Electronics:**
- | Notes | Page 36 |
|-----------------------|---------|
| ESCON Mod. 50/4 EC-S | 487 |
| ESCON Module 50/5 | 487 |
| ESCON Mod. 50/8 (HE) | 488 |
| ESCON 50/5 | 489 |
| ESCON 70/10 | 489 |
| DEC Module 50/5 | 491 |
| EPOS4 Mod./Comp. 50/5 | 499 |
| EPOS4 Mod./Comp. 50/8 | 499 |
| EPOS4 50/5 | 501 |
| EPOS4 70/15 | 501 |
| EPOS2 P 24/5 | 504 |

- Encoder 16 EASY/XT**
- 128 - 1024 CPT, 3 channels
- Page 450/452
- Encoder 16 EASY Absolute/XT**
- 4096 steps
- Page 454/456
- Encoder 16 RIO**
- 1024 - 32768 CPT, 3 channels
- Page 467
- Encoder AEDL 5810**
- 1024 - 5000 CPT, 3 channels
- Page 470
- Encoder HEDL 5540**
- 500 CPT, 3 channels
- Page 477